Bayesian Approaches *Data Mining Selected Technique*

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Probabilistic Bases

Review the fundamentals of Probability Theory.

- A is a Boolean-valued variable if A denotes an event, and there is some degree of uncertainty as to whether A occurs.
- \square P(A) denotes the fraction of possible worlds in which A is true.
- The axioms of general probability:
 - $\bullet 0 \le P(A) \le 1.$
 - $\blacksquare P(true) = 1.$
 - $\blacksquare P(false) = 0.$
 - $\blacksquare P(\neg A) + P(A) = 1.$
 - $\blacksquare P(A \cup B) = P(A) + P(B) P(A \cap B).$



Probabilistic Bases

Multivalued Random Variables.

A is a *random variable with arity* k if it can take on exactly one value out of v_1, v_2, \ldots, v_k .

$$\square P(A = v_i \cap A = v_j) = 0 \text{ if } i \neq j.$$

$$P(A = v_1 \cup A = v_2 \cup \dots A = v_k) = \sum_{i=1}^k P(A = v_i) = 1.$$

$$P(B) = \sum_{i=1}^k P(B \cap A = v_i).$$



Bayes Rule

Conditional Probability and Bayes Rule.

P(A|B) is a fraction of worlds in which A is true given B is true.
P(A|B) = \frac{P(A \cap B)}{P(B)} \Rightarrow P(A \cap B) = P(A|B)P(B) (Chain Rule)
P(B|A) = \frac{P(A|B)P(B)}{P(A)} (Bayes Rule)
P(B|A) = \frac{P(A|B)P(B)}{P(A|B)P(B)+P(A|\gam B)P(\gam B)}.
P(B|A \cap C) = \frac{P(A|B \cap C)P(B \cap C)}{P(A \cap C)}.



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- Problem:
 - The Joint Estimator just mirrors the training data overfitting.
 - Naïve Estimator assumes each attribute is independent.





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- M_i estimates $P(X_1, X_2, \ldots, X_m | Y = v_i)$.



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Posterior probability:

$$P(Y = v | X_1 = u_1, \dots, X_m = u_m)$$

$$= \frac{P(X_1 = u_1, \dots, X_m = u_m | Y = v) P(Y = v)}{P(X_1 = u_1, \dots, X_m = u_m)}$$

$$= \frac{P(X_1 = u_1, \dots, X_m = u_m | Y = v) P(Y = v)}{\sum_{i=1}^n P(X_1 = u_1, \dots, X_m = u_m | Y = v_i) P(Y = v_i)}.$$



Bayes Classifier Model.

- Learn the distribution over inputs for each value Y^* .
- Calculate $P(X_1, X_2, \ldots, X_m | Y = v_i)$

Estimate $P(Y = v_i)$ as a fraction of records with $Y = v_i$.

For a new prediction:

 $Y^{predict} = \arg\max_{v} P(X_1 = u_1, \dots, X_m = u_m | Y = v) P(Y = v).$

* Learn the distribution is done by a Density Estimator here.



Gaussian Bayes Classifier

Gaussian Bayes Classifier Bases.

- Generate the output by drawing $y_i \sim Multinomial(p_1, p_2, \ldots, p_n)$
- Generate the inputs from a Gaussian PDF that depends on the value of y_i : $x_i \sim N(\mu_i, \Sigma_i)$.

$$P(y=i|\mathbf{X}) = \frac{p(\mathbf{X}|y=i)p(y=i)}{p(\mathbf{X})}.$$

$$P(y=i|\mathbf{X}) = \frac{\frac{1}{(2\pi)^{m/2} \|S_i\|^{1/2}} e^{-\frac{1}{2}(x_k - \mu_i)^T S_i(x_k - \mu_i)} p_i}{p(\mathbf{X})}$$

where μ_i and S_i is the mean and variance by taking *MLE Gaussian* ($\mu_i^{mle}, \Sigma_i^{mle}$).



Gaussian Bayes Classifier

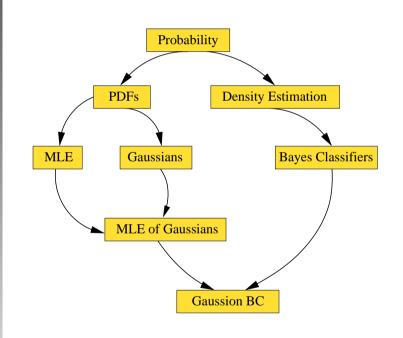
Gaussian BC Discussion.

- Number of parameters is quadratic with number of dimensions generally because of the covariance matrix.
- Normalize Gaussian may give O(1) covariance parameters.
- Gaussian DE and BC inputs require to be *Real-valued*.
- Gaussian Naïve or Gaussian Joint can accept both categorical and real-valued inputs.



Bayes Classifiers Methods

Different Bayes Classifiers have been developed.



BC Road Map



- Naïve Bayes Classifier.
- Gaussian Bayes Classifier.
- Other joint Bayes Classifier possible.



Introduction to Bayes Nets. (A Bayes Net Example)

- A Bayes net (or Belief network) is an augmented directed acyclic graph, represented by the vertex set V and directed edge set E.
- There is no loops allowed. And each vertex $v \in V$ represents a random variable.
- A probability distribution table indicating how the probability of this variable's values depends on all possible combinations of parental values.
- Two variable v_i and v_j may still correlated even if they are not connected.



Each variable v_i is conditionally independent of all non-descendants, given its parents.

Building a Bayes Net.



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Choose a set of relevant variables.

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Assume the variables are X_1, X_2, \ldots, X_n (where X_1 is the first, X_i is the *i*th).

for i = 1 to n:

Add the X_i vertex to the network

- Set $Parent(X_i)$ to be a minimal subset of X_1, \ldots, X_{i-1} , such that we have conditional independence of X_i and all other members of X_1, \ldots, X_{i-1} given $Parents(X_i)$
- Define the probability table of

 $P(X_i = k \mid Assignments \ of \ Parent(X_i)).$



Bayesian Networks Discussion.

Independence and conditional independence.

Inference can be calculated.

- Enumerating entries is exponential in the number of variables.
- The stochastic simulation and likelihood weighting.



Conclusion

Topics we have discussed here:

- Probabilistic bases and Bayes Rule
- Density Estimation
- Bayes Model
- Bayes Classifiers
- Bayesian Networks



Bayes, Thomas(1763)





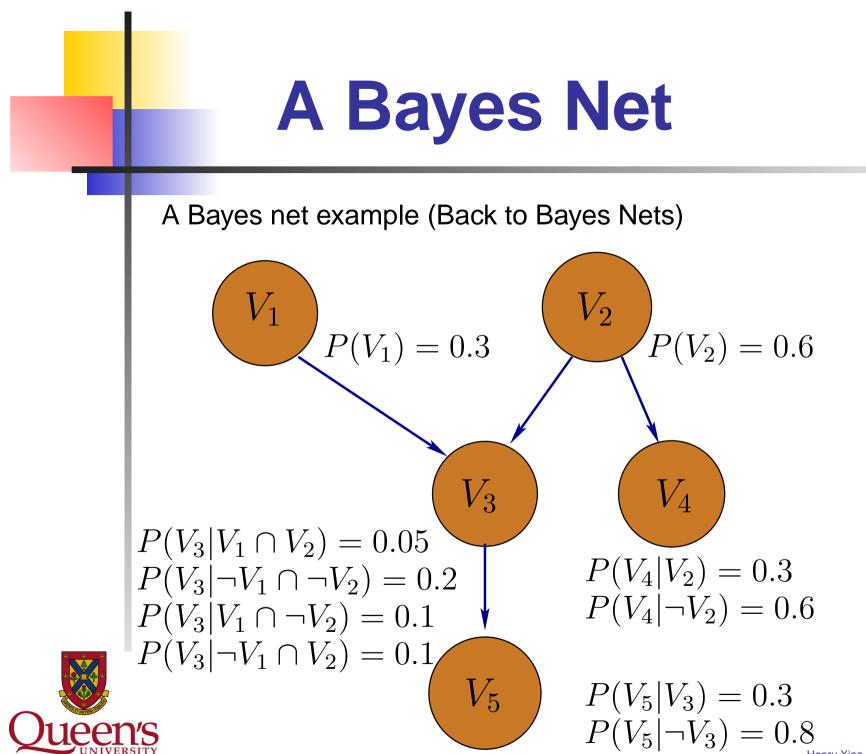
Questions regarding Bayesian Approaches?

Information Site: http://www.cs.queensu.ca/home/xiao/dm.html

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Thank you





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